

Unidad de control	KR C4
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Technical drawing of the R392 robot arm showing dimensions and reach. The drawing includes the following dimensions and angles:

- Vertical dimensions: 3702, 1400, 1100, 65, 1502, 600, 1470, 3202.
- Horizontal dimensions: 1200, 372, 4225, R392.
- Angles: -110° , $+145^\circ$, -130° , $+17.5^\circ$.

A graph showing the relationship between L_{xy} (Y-axis, 0 to 500 mm) and L_z (X-axis, 0 to 700 mm) for different weights. The curves represent the maximum L_{xy} for a given L_z and weight. The weights are 800 kg, 840 kg, 880 kg, 920 kg, 960 kg, and 1000 kg. The curves show that for a given weight, the maximum L_{xy} decreases as L_z increases. The curves are labeled with their respective weights.

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